



# Machine Learning-aided Optimal Control of a Qubit under non-Markovian dynamics

Riccardo Cantone<sup>a,\*</sup>, Shreyasi Mukherjee<sup>a</sup>, Luigi Giannelli<sup>a,b</sup>, Elisabetta Paladino<sup>a,b,c</sup>, Giuseppe Falci<sup>a,b,c</sup>

(a) Department of Physics and Astronomy "Ettore Majorana", University of Catania, Via S. Sofia 64, I-95123 Catania, Italy

(b) INFN, Catania Section, I-95123 Catania, Italy

(c) CNR-IMM, Via S. Sofia 64, I-95123 Catania, Italy



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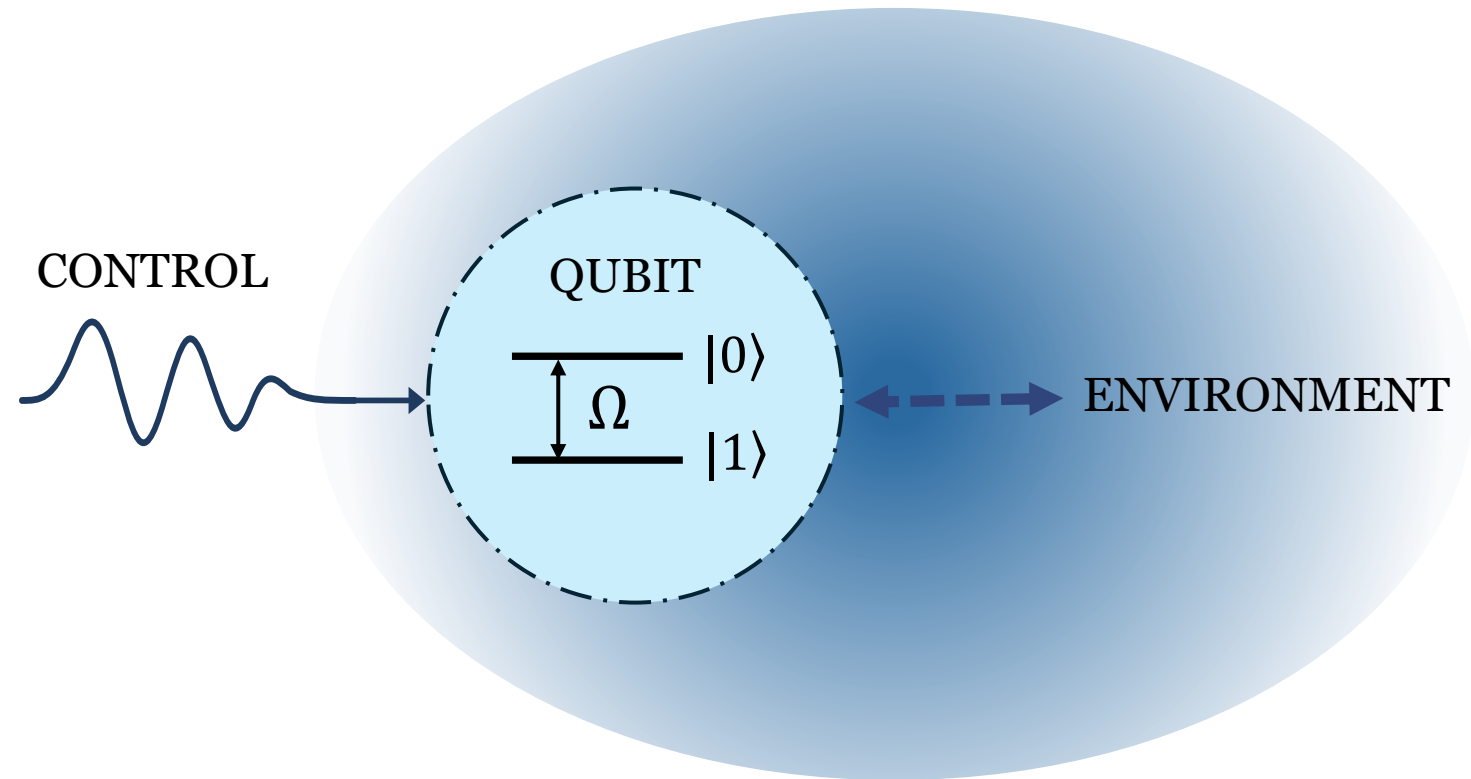
Quantum Technologies at UniCT

# Control of open quantum systems



## The challenge

- Qubits interact with control and environment.
- **Non-Markovian** dynamics: memory effects render standard approaches insufficient.
- Environmental noise causes **decoherence**.
- Quantum gates require precise control pulses.





# Control of open quantum systems



## Whitebox

### Pros:

- Rigorous.
- Interpretable.

### Cons:

- For open systems, it often requires strong assumptions and/or approximations.
- Hard to model non-Markovian dynamics.

E.g.

$$\dot{\rho} = -i[H(t), \rho] + \sum_j \gamma_j (L_j \rho L_j^\dagger - \frac{1}{2}\{L_j^\dagger L_j, \rho\})$$



# Control of open quantum systems



## Whitebox

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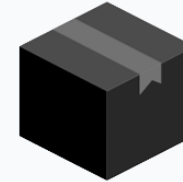
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## Blackbox

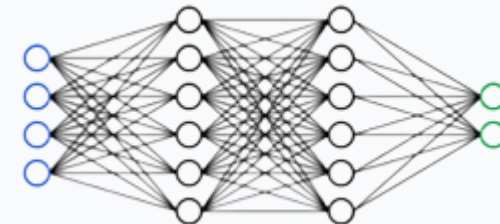
### Pros:

- Doesn't require any a priori hypothesis.
- Highly flexible.

### Cons:

- Lacks interpretability.
- Often requires large training datasets.

E.g.

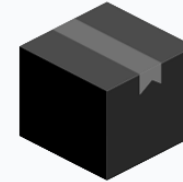




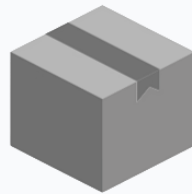
# Control of open quantum systems



**Whitebox**



**Blackbox**



**Graybox**

- Rigor and interpretability of the whitebox approach.
- Requires no assumptions on the system.
- Flexibility of the blackbox approach.
- Requires less training data than the blackbox approach.

# Open System Hamiltonian

$$H = \underbrace{\frac{\Omega}{2}\sigma_z}_{H_0: \text{intrinsic term}} + \underbrace{F_x(t)\cos(\omega_d t + \phi)\sigma_x + F_y(t)\cos(\omega_d t + \phi)\sigma_y}_{H_{ctrl}(t): \text{control term}} + \underbrace{g\beta(t)\sigma_z}_{H_1: \text{noise term}}$$

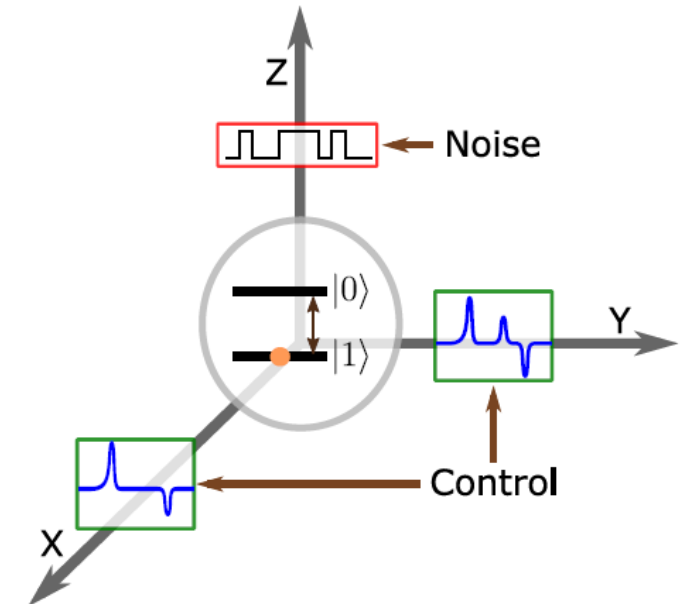
with  $\omega_d$  drive frequency.

- Noise applied along the  $z$ -axis of the Bloch sphere: **dephasing noise**.
- Control drive applied along the  $x$ - and  $y$ -axes.

By moving to a suitable rotating frame and applying the rotating wave approximation, with a resonant drive, we get:

$$\tilde{H} = f_x(t)\sigma_x + f_y(t)\sigma_y + g\beta(t)\sigma_z$$

with  $f_x(t) = \frac{F_x(t)}{2}$ ,  $f_y(t) = \frac{F_y(t)}{2}$ .



# Open System dynamics

## The goal

Predict the expectation value  $\mathbb{E}[O(T)]_\rho$  of observable  $O$  at time  $T$ :

$$\mathbb{E}[O(T)]_\rho = \text{tr}_S[V_O U_{ctrl}(T)\rho(T)U_{ctrl}^\dagger(T)O] \quad \text{where} \quad U_{ctrl}(T) = \mathcal{T}_+ \exp\left(-i \int_0^T H_{ctrl}(s)ds\right)$$

For classical noise and a traceless observable  $V_O = O^{-1}QDQ^\dagger$ , where

$$D = \begin{pmatrix} \mu & 0 \\ 0 & -\mu \end{pmatrix}, \quad Q = \begin{pmatrix} e^{i\psi} & 0 \\ 0 & e^{-i\psi} \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} e^{i\Delta} & 0 \\ 0 & e^{-i\Delta} \end{pmatrix}$$

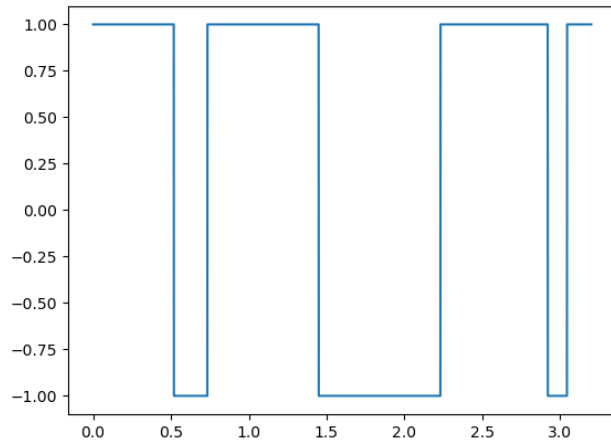
Calculation of  $V_O$  is reduced to finding the **four parameters**  $\Delta, \mu, \psi, \theta$ .

For  $O \in \{\sigma_x, \sigma_y, \sigma_z\}$  and  $\rho(0) \in \{|0_x\rangle, |1_x\rangle, |0_y\rangle, |1_y\rangle, |0_z\rangle, |1_z\rangle\}$  calculation of  $\mathbb{E}[O(T)]_\rho$  yields tomographically complete information on  $\rho(T)$ .

# Noise models

## Random Telegraph Noise (RTN)

- Stochastic, binary, discrete-state process.
- Non-Gaussian, Markovian.



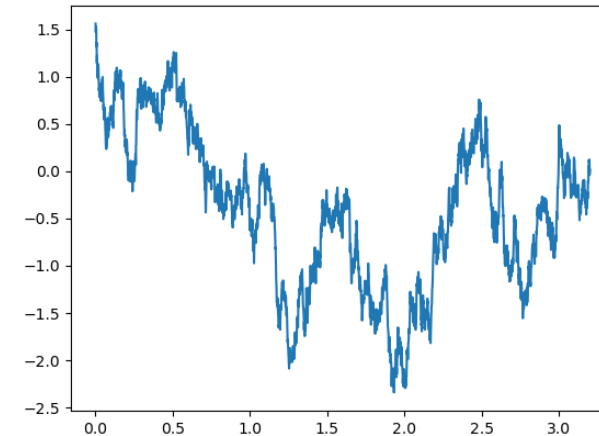
$$\xi(t) = \xi(0)(-1)^{n(0,t)} \quad \mathbb{P}[n(0,t) = k] = \frac{(\gamma t)^k}{k!} e^{-\gamma t}$$

$$\xi(0) = \pm 1$$

$$\langle \xi(t_1)\xi(t_2) \rangle = e^{-2\gamma|t_1-t_2|}$$

## Ornstein-Uhlenbeck Noise

- Stochastic, continuous, Markovian process.
- Gaussian.
- Mean-reverting.



$$X(t) = X(0)e^{-kt} + \mu(1 - e^{-kt}) + \sqrt{D} \int_0^t e^{-k(t-t')} dW(t')$$

$$\langle X(t_1)X(t_2) \rangle \rightarrow \frac{D}{2k} e^{-k|t_1-t_2|}$$

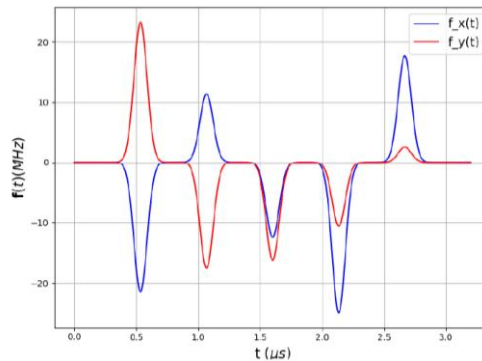
# Model training and Optimal Control

## Training

- Data produced through Monte Carlo simulations.
- Input: random set of control pulse amplitudes.
- Output: fidelities for a universal set of 1-qubit gates.
- Two-axis control.
- Control achieved through Gaussian pulses:

$$f_{\alpha}(t) = \sum_{k=1}^N A_{k,\alpha} \exp\left(-\frac{(t-\tau_k)^2}{\sigma^2}\right)$$

- Control parameters:  $N = 5$ ,  $\tau_k = \frac{k}{N+1}T$ ,  $\sigma = \frac{T}{12N}$ .
- Dataset generated for various values of the coupling strength  $g$ .



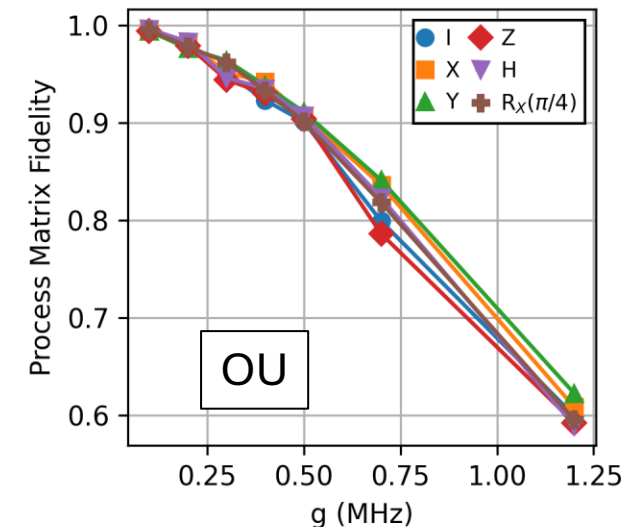
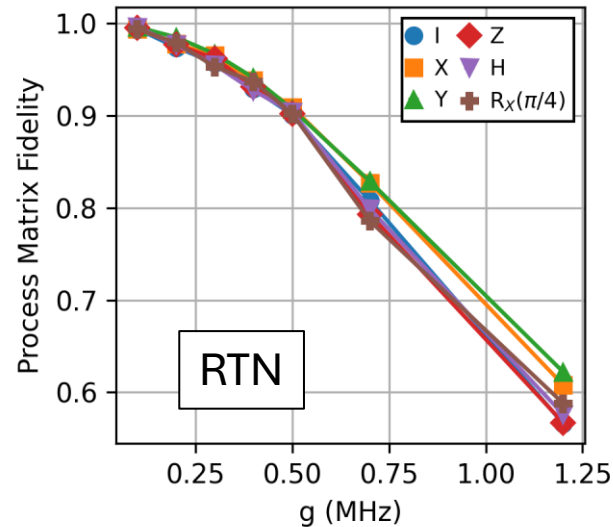
## Optimal Control

### Approach:

- After training, the model is used as a fast dynamics emulator.
- Optimization of pulse parameters  $u(t)$  to implement a universal set of single qubit gates.

### Optimization criterion:

- Cost functional:  $J(u, \Theta; G) = 1 - F(u, \Theta; G)$ , where  $F = \text{tr}(\chi_{actual}^\dagger, \chi_{target})$ .
- Optimization done using L-BFGS-B method.





# Conclusions & Outlook

## Summary

- Graybox model accurately emulates qubit dynamics across a wide range of coupling strengths ( $g = 0.1 - 1.2$  MHz).
- Gate fidelities above 99% at the lowest considered values of  $g$ . Remaining above 90% up to  $g = 0.5$  MHz.
- Similarity in results between RTN and OU shows robustness of the model.

## Future developments

- Adaptation to real-device constraints.
- Extension to multi-qubit and multi-level systems.
- Application to dynamical decoupling protocols.



Thank you  
for your  
attention.

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